# **NAG Toolbox for MATLAB**

#### s18ae

# 1 Purpose

s18ae returns the value of the modified Bessel Function  $I_0(x)$ , via the function name.

## 2 Syntax

[result, ifail] = s18ae(x)

## 3 Description

s18ae evaluates an approximation to the modified Bessel Function of the first kind  $I_0(x)$ .

**Note:**  $I_0(-x) = I_0(x)$ , so the approximation need only consider  $x \ge 0$ .

The function is based on three Chebyshev expansions:

For  $0 < x \le 4$ ,

$$I_0(x) = e^x \sum_{r=0}^{\prime} a_r T_r(t),$$
 where  $t = 2\left(\frac{x}{4}\right) - 1.$ 

For  $4 < x \le 12$ ,

$$I_0(x) = e^x \sum_{r=0}^{7} b_r T_r(t),$$
 where  $t = \frac{x-8}{4}$ .

For x > 12,

$$I_0(x) = \frac{e^x}{\sqrt{x}} \sum_{r=0}^{\prime} c_r T_r(t), \qquad \text{where } t = 2\left(\frac{12}{x}\right) - 1.$$

For small x,  $I_0(x) \simeq 1$ . This approximation is used when x is sufficiently small for the result to be correct to *machine precision*.

For large x, the function must fail because of the danger of overflow in calculating  $e^x$ .

#### 4 References

Abramowitz M and Stegun I A 1972 Handbook of Mathematical Functions (3rd Edition) Dover Publications

### 5 Parameters

#### 5.1 Compulsory Input Parameters

1:  $\mathbf{x} - \mathbf{double}$  scalar

The argument x of the function.

## 5.2 Optional Input Parameters

None.

### 5.3 Input Parameters Omitted from the MATLAB Interface

None.

[NP3663/21] s18ae.1

s18ae NAG Toolbox Manual

# 5.4 Output Parameters

1: result – double scalar

The result of the function.

2: ifail - int32 scalar

0 unless the function detects an error (see Section 6).

# 6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail = 1

 $\mathbf{x}$  is too large. On soft failure the function returns the approximate value of  $I_0(x)$  at the nearest valid argument.

# 7 Accuracy

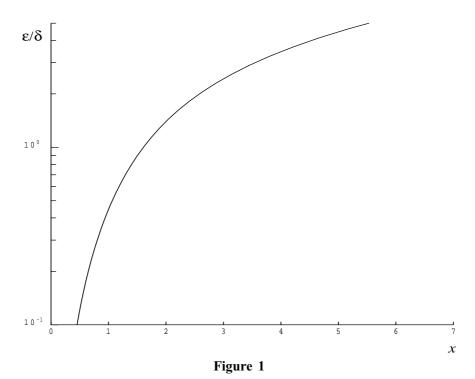
Let  $\delta$  and  $\epsilon$  be the relative errors in the argument and result respectively.

If  $\delta$  is somewhat larger than the *machine precision* (i.e., if  $\delta$  is due to data errors etc.), then  $\epsilon$  and  $\delta$  are approximately related by:

$$\epsilon \simeq \left| \frac{x I_1(x)}{I_0(x)} \right| \delta.$$

Figure 1 shows the behaviour of the error amplification factor

$$\left| \frac{xI_1(x)}{I_0(x)} \right|$$



However if  $\delta$  is of the same order as *machine precision*, then rounding errors could make  $\epsilon$  slightly larger than the above relation predicts.

s18ae.2 [NP3663/21]

For small x the amplification factor is approximately  $\frac{x^2}{2}$ , which implies strong attenuation of the error, but in general  $\epsilon$  can never be less than the *machine precision*.

For large x,  $\epsilon \simeq x\delta$  and we have strong amplification of errors. However the function must fail for quite moderate values of x, because  $I_0(x)$  would overflow; hence in practice the loss of accuracy for large x is not excessive. Note that for large x the errors will be dominated by those of the standard function EXP.

## **8** Further Comments

None.

# 9 Example

```
x = 0;
[result, ifail] = s18ae(x)

result =
    1
ifail =
    0
```

[NP3663/21] s18ae.3 (last)